







## COMPLETELY INTEGRATED **COLLABORATIVE MOBILE**

MANIPULATOR (CMM), FOR INDUSTRIAL TASKS

PICK & PLACE METROLOGY PART FEEDING INDUSTRIAL APPLICATIONS R & D

## TECHNICAL SPECIFICATIONS

## MECHANICAL



Dimensions 978 x 776 x 944 mm

Weight 115 kg + 11,2 kg

Payload Up to 250 kg

Speed **1,5 m/s** 

Environment Indoor

Enclosure class **IP52** 

Autonomy Up to 12 h

Batteries LiFePO<sub>4</sub> 15Ah@48VDC or

30Ah@48VDC

Traction motors 4 x 500 W

brushless servomotors

wtih safety brake

Temperatura range 0° to + 50°C

Max. slope 15 %







## CONTROL

Controller Open architecture ROS

**Integrated CPU with Linux** 

Communication WiFi 02.11a/b/g/n/ac

Bluetooth 5.1 (5G/4G optional)

Connectivity USB, RJ45, power supplies 12, 24

**VDC** and batteries

Ready for plug and play

integration of Universal Robots™

arms (OEM DC Version)

UR3E

Payload 3 kg

Reach 500 mm

Ready for integration of compatible accessories arm available in ROS Components

store









