

RS-Ruby Plus is a new 128-beam mechanical LiDAR specifically designed for L4+ autonomous driving. Compared with RS-Ruby, it has reduced volume by 50%, weight by 52% and power consumption by 33% for a greatly improved performance.

RS-Ruby Plus has achieved a breakthrough in detection range, reaching 240 m at 10% reflectivity, making it 20% higher than its competitors. It can detect vehicles and pedestrians 200 m away with a maximum resolution of 0.1°, greatly increasing the response time for high-speed autonomous driving.

Additionally, RS-Ruby Plus's stronger ground detection capability is complemented by excellent reflectivity performance to achieve a maximum 85 m extra-long traffic lane line detection.

Product Advantage







Up to $0.1^{\circ} \times 0.1^{\circ}$ Angular Resolution

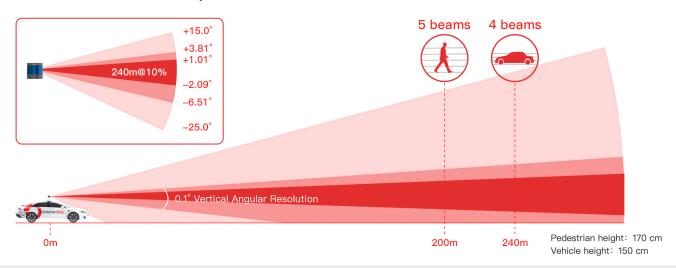


Maximum 85 m traffic lane line detection



Resists Interference of Other LiDAR & Ambient Light

104 channels with 0.1° vertical angular resolution; 32 channels in the middle with 240 m at 10% reflectivity



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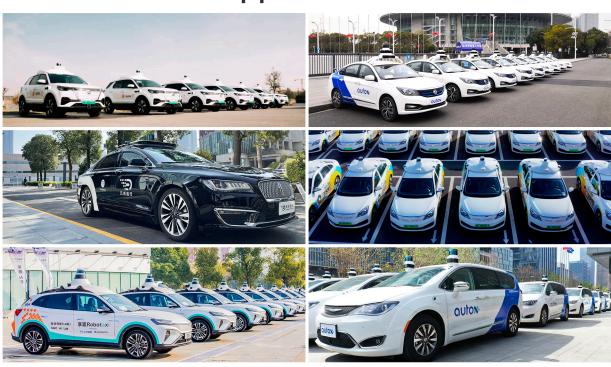


Sensor					
# of Lines	128	Vertical Resolution	0.1° (-6.51° ~ +3.81°)		
Laser Wavelength	905nm	Horizontal FoV	360°		
Laser Safety	Class 1 eye safe	Horizontal Resolution ⁵	[Balance] 0.2° / 0.4° [High Performance] 0.1° / 0.2°		
Blind Spot	≤0.4m	Frame Rate	10Hz/ 20Hz		
Vertical FoV	40° (-25° ~+15°)	Rotation Speed	600/1200rpm (10/20Hz)		
Range ⁶	240m(240m@10% NIST)				
Range Accuracy ²	±3cm (3sigma, 0.4m to 1 m) ±2cm (3sigma, 1 m to 240m)				

Output				
Points Per Second	[Balance] ~2,304,000pts/s (Single Return) ~4,608,000pts/s (Dual Return) [High Performance] ~4,608,000pts/s (Single Return) ~9,216,000pts/s (Dual Return)			
Ethernet Connection	1000M Base T1			
Output	UDP packets over Ethernet			
UDP Packet include	Spatial Coordinates, Intensity, Timestamp, etc.			

Mechanical					
Operating Voltage	9–32V	Dimensions	Ф125mm * H128mm		
Power Consumption ³	[Balance] 27W [High Performance] 30W	Operating Temperature ⁴	-40°C ~ +60°C		
Weight(without cabling)	~1.85 kg	Storage Temperature	-40°C ~ +85°C		
Time Synchronization	\$GPRMC with 1pps, PTP & gPTP	Ingress Protection	IP67、IP6K9K		

Applications



- 1. The following data is only for mass-produced products. Any samples, testing machines and other non-mass-produced versions may not be referred to this specification. If you have any questions, please contact RoboSense sales.
- 2. The measurement target of accuracy is a 50% NIST diffuse reflectance target under 100 klux light. The test performance is dependent on circumstantial factors, including temperature, range, target reflectivity and other variables
- 3. The power consumption is tested under a 10 Hz frame rate. The results are dependent on circumstantial factors, including temperature, range, target reflectivity and other variables.
- 4. The operational temperature is dependent on circumstantial factors, including sun load, air flow and other variables. 5. The corresponding operating frequency of $0.2^{\circ}/0.4^{\circ}$ is 10 Hz/20 Hz.
- 6. The detection range is measured under 100 klux light. The range performance is dependent on circumstantial factors, including temperature, range, target reflectivity and other variables.